









HDR in Microsoft Excel?! Kevin Chen • !!Con 2017

Motivation

• N/A

Background







0

Mark III

Reciprocity Open the shutter 2x longer S 2x more light





Nonlinearity 2x more light S 2x bigger number in JPG





Recovering

ABSTRACT

We present a method of r maps from photographs ta ment. In our method, mul with different amounts of ferently exposed photograp imaging process, up to fact procity. With the known re the multiple photographs in map whose pixel values are in the scene. We demonstr



both photochemical and digital imaging processes. We discuss how this work is applicable in many areas of computer graphics involving digitized photographs, including image-based modeling, image compositing, and image processing. Lastly, we demonstrate a few applications of having high dynamic range radiance maps, such as synthesizing realistic motion blur and simulating the response of the human visual system.

Photographs

the scene. For example, if t is unlikely that it observed lly an unknown, nonlinear n the scene becomes pixel

w beforehand because it is inear mappings that occur itional camera (see Fig. 1), a latent image. The film is ge into variations in transcan then be digitized using





log(amount of light)















digital number = f(brightness • shutter open time)

 $Z = f(E \cdot \Delta t)$

 $f^{-1}(Z) = E \cdot \Delta t$ flip it!

 $g(Z) = E \cdot \Delta t$







Very Big Matrix[™]





 $A \times \mathbf{x} = \mathbf{b}$





MatheAss

One of the most popular Shareware Math Programs in Germany

Pseudo Inverse Matrix

If the columns of a matrix A are linearly independent, so $A^{T} A$ is invertible and we obtain with the following formula the pseudo inverse:

States and the second states and the second

Here A^+ is a left inverse of A, what means: $A^+ A = E$.

Microsoft Excel TimeTM

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2		0	-11.89	N/A							
3		1	-11.56	0.00							11 .
4		2	-11.22	0.00							177
5		3	-10.89	0.00							
6		4	-10.55	0.00		17					
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14		12	-7.87	0.00							
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17		15	-6.86	0.00	0.00		50			150	
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22		20	-5.24	-0.02		1					
23		21	-4.95	-0.02	-6.00						
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25		23	-4.42	-0.02							
26		24	-4.19	-0.02	-8.00						
27		25	-3.97	-0.02							
28		26	-3.77	-0.02	-10.00						-
29		27	-3.59	-0.02							
30		28	-3.42	-0.01	-12.00						
31		29	-3.26	-0.01							
32		30	-3.12	-0.01	-14.00						
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